

CS 423 Operating System Design: Scheduling

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CS 423: Operating Systems Design

Scheduling



- A forever topic in Computer Systems and Life
 - Uniprocessor: I00 threads in the ready queue which one to run next?
 - Multiprocessor: 400 threads in the ready queues of four cores – which one to run next on which core?
 - Cluster: 1000 MapReduce jobs which one to run on which machine and on which core?
 - Datacenters: 10000 user request which one to run on which datacenter on which cluster on which machine?

More complexity

- Jobs/requests are not created equal.
 - Some are more important than the others
- Jobs/requests could have deadlines
 - Finishing late means nothing but wasting resources.
- Jobs/requests have constraints
 - Affinity is important same node and same PCIe switch for GPUs
- Workloads could be very different.

Scheduling



- Always an active research topic
 - Everyone wants run more jobs with less resources

 In this class, we are going to focus on the simplest setup – a uniprocessor

What Are Scheduling Goals?

- What are the goals of a scheduler?
- Scheduling Goals:
 - Generate illusion of concurrency



- Maximize resource utilization (e.g., mix CPU and I/O bound processes appropriately)
- Meet needs of both I/O-bound and CPU-bound processes
 - Give I/O-bound processes better interactive response
 - Do not starve CPU-bound processes
- Support Real-Time (RT) applications

- Task/Job
 - Something that needs CPU time: a thread associated with a process or with the kernel...
 - ... a user request, e.g., mouse click, web request, shell command, ...
- Latency/response time
 - How long does a task take to complete?
- Throughput
 - How many tasks can be done per unit of time?

Overhead

- How much extra work is done by the scheduler?
- Fairness
 - How equal is the performance received by different users?
- Predictability
 - How consistent is the performance over time?
- Starvation
 - A task 'never' receives the resources it needs to complete
 - Not very fair : (



- Workload
 - Set of tasks for system to perform
- Work-conserving
 - Resource is used whenever there is a task to run
 - For non-preemptive schedulers, work-conserving is not always better





- Non-preemptive scheduling:
 - The running process keeps the CPU until it voluntarily gives up the CPU
 - process exits
 - switches to blocked state
 - 1 and 4 only (no 3)
- Preemptive scheduling:
 - The running process can be interrupted and must release the CPU (can be forced to give up CPU)





- Scheduling algorithm
 - takes a workload as input
 - decides which tasks to do first
 - Performance metric (throughput, latency) as output
 - Only preemptive, work-conserving schedulers to be considered



First In First Out (FIFO)



- Schedule tasks in the order they arrive
 - Continue running them until they complete or give up the processor

On what workloads would FIFO be particularly bad?

Shortest Job First (SJF)



- Always do the task that has the shortest remaining amount of work to do
 - Often called Shortest Remaining Time First (SRTF)

- Suppose we have five tasks arrive one right after each other, but the first one is much longer than the others
 - Which completes first in FIFO? Next?
 - Which completes first in SJF? Next?

FIFO vs. SJF



Round Robin (RR)

- Each task gets resource for a fixed period of time (time quantum)
 - If task doesn't complete, it goes back in line
- Characteristics of scheduler change depending on the time quantum size
 - What if time quantum is too short?
 - One instruction?
 - What if time quantum is too long?
 - Infinite?













Scheduling



- Basic scheduling algorithms
 - FIFO (FCFS)
 - Shortest job first
 - Round Robin

Scheduling

Basic scheduling algorithms

- FIFO (FCFS)
- Shortest job first
- Round Robin

What is an optimal algorithm in the sense of maximizing the number of jobs finished (i.e., minimizing average response time)?

FIFO vs. SJF





Scheduling

Basic scheduling algorithms

- FIFO (FCFS)
- Shortest job first
- Round Robin

Assuming zero-cost to time slicing, is Round Robin always better than FIFO?

RR v. FIFO (fixed size tasks)



Starvation, Sample Bias

- Suppose you want to compare two scheduling algorithms
 - Create some infinite sequence of arriving tasks
 - Start measuring
 - Stop at some point
 - Compute average response time as the average for completed tasks between start and stop
- Is this valid or invalid?

Sample Bias Solutions

- Measure for long enough that # of completed tasks >> # of uncompleted tasks
 - For both systems!
- Start and stop system in idle periods
 - Idle period: no work to do
 - If algorithms are work-conserving, both will complete the same tasks

Round Robin = Fairness?



Is Round Robin the fairest possible algorithm?

What is fair?

- FIFO?
- Equal share of the CPU?
- What if some tasks don't need their full share?
- Minimize worst case divergence?
- Time task would take if no one else was running
- Time task takes under scheduling algorithm

Fairness needs to be defined.

- 4 kids share a cake.
 - Each gets 25% of the cake.
 - Quite fair!

- There is one little kids and the kid can only eat 10% of the cake.
 - We either force her to eat the 25% -- to be fair
 - Or we give 15% remaining to the other 3 kids.
 - Min-max fairness

- The *least* demanding one will get its fair share first
- After this, the next least demanding one will get its fair share first
- And so on...

- Kid 1: 20%
- Kid 2: 26%
- Kid 3: 40%
- Kid 4: 50%

- 100% -> 25% each kid
 - 20% -> 5% left -> 1.666666% to the other three
 25%
 25%

- Kid 1: 20%
- Kid 2: 26%
- Kid 3: 40%
- Kid 4: 50%

- 100% -> 25% each kid
 - <u>20%</u>
 <u>26%</u>
 27%
 27%

- How do we balance a mixture of repeating tasks?
 - Some I/O bound, need only a little CPU
 - Some compute bound, can use as much CPU as they are assigned
- One approach: maximize the minimum allocation given to a task
 - If any task needs less than an equal share, schedule the smallest of these first
 - Split the remaining time using max-min
 - If all remaining tasks need at least equal share, split evenly

Mixed Workloads??



Multi-Level Feedback Queue

- Goals:
 - Responsiveness
 - Low overhead
 - Starvation freedom
 - Some tasks are high/low priority
 - Fairness (among equal priority tasks)
- Not perfect at any of them!
 - Used in Linux (and probably Windows, MacOS)

Multi-Level Feedback Queue

- Set of Round Robin queues
 - Each queue has a separate priority
- High priority queues have short time slices
 - Low priority queues have long time slices
- Scheduler picks first thread in highest priority queue
- Tasks start in highest priority queue
 - If time slice expires, task drops one level

Multi-Level Feedback Queue





Summary



- FIFO is simple and minimizes overhead.
- If tasks are variable in size, then FIFO can have very poor average response time.
- If tasks are equal in size, FIFO is optimal in terms of average response time.
- Considering only the processor, SJF is optimal in terms of average response time.
- SJF is pessimal in terms of variance in response time.

Summary



- If tasks are variable in size, Round Robin approximates SJF.
- If tasks are equal in size, Round Robin will have very poor average response time.
- Tasks that intermix processor and I/O benefit from SJF and can do poorly under Round Robin.

Summary

- Max-Min fairness can improve response time for I/Obound tasks.
- Round Robin and Max-Min fairness both avoid starvation.
- By manipulating the assignment of tasks to priority queues, an MFQ scheduler can achieve a balance between responsiveness, low overhead, and fairness.
- Is MFQ optimally fair??

