

CS 423 Operating System Design: Concurrency

Tianyin Xu

* Thanks for Prof. Adam Bates for the slides.

Concurrency vs Parallelism



Two tasks

- I. Get a visa
- 2. Prepare slides

- I. Sequential execution
- 2. Concurrent execution
- 3. Parallel execution
- 4. Concurrent but not parallel
- 5. Parallel but not concurrent
- 6. Parallel and concurrent

Why Concurrency?



- Servers
 - Multiple connections handled simultaneously
- Parallel programs
 - To achieve better performance
- Programs with user interfaces
 - To achieve user responsiveness while doing computation
- Network and disk bound programs
 - To hide network/disk latency

Definitions

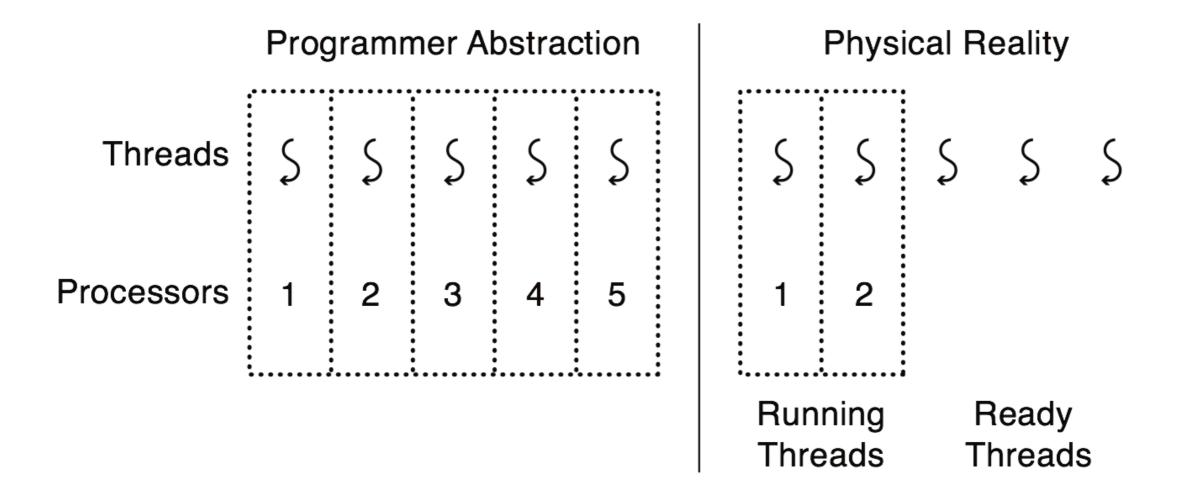


- Thread: A single execution sequence that represents a separately schedulable task.
 - Single execution sequence: intuitive and familiar programming model
 - separately schedulable: OS can run or suspend a thread at any time.
 - Schedulers operate over threads/tasks, both kernel and user threads.
- Does the OS protect all threads from one another?

The Thread Abstraction



- Infinite number of processors
- Threads execute with variable speed



Programmer vs. Processor View



Programmer View

Programmer's View

.

x = x + 1; y = y + x;z = x + 5y;

.

Possible
Execution
#1
...
...
...
x = x + 1;
y = y + x;
z = x + 5y;

Possible
Execution
#2
...
x = x + 1;

Thread is suspended.
Other thread(s) run.

Thread is resumed.

$$y = y + x;$$

 $z = x + 5y;$

Possible Execution #3

x = x + 1;y = y + x;

Thread is suspended. Other thread(s) run.

Thread is resumed.

z = x + 5y;

Variable Speed: Program must anticipate all of these possible executions

Possible Executions



Processor View

One Execution	Another Execution
Thread 1	Thread 1
Thread 2	Thread 2
Thread 3	Thread 3
Another Execution	
Thread 1	
Thread 2	
Thread 3	

Something to look forward to when we discuss scheduling!

Thread Ops



- thread_create(thread, func, args)
 Create a new thread to run func(args)
- thread_yield()
 Relinquish processor voluntarily
- thread_join(thread)
 In parent, wait for forked thread to exit, then return
- thread_exit
 Quit thread and clean up, wake up joiner if any

Ex: threadHello



```
#define NTHREADS 10
thread t threads[NTHREADS];
main() {
    for (i = 0; i < NTHREADS; i++) thread_create(&threads[i], &go, i);</pre>
    for (i = 0; i < NTHREADS; i++) {
        exitValue = thread join(threads[i]);
        printf("Thread %d returned with %ld\n", i, exitValue);
    printf("Main thread done.\n");
}
void go (int n) {
    printf("Hello from thread %d\n", n);
    thread exit(100 + n);
    // REACHED?
```

Ex: threadHello output



```
bash-3.2$ ./threadHello
Hello from thread 0
Hello from thread 1
Thread 0 returned 100
Hello from thread 3
Hello from thread 4
Thread 1 returned 101
Hello from thread 5
Hello from thread 2
Hello from thread 6
Hello from thread 8
Hello from thread 7
Hello from thread 9
Thread 2 returned 102
Thread 3 returned 103
Thread 4 returned 104
Thread 5 returned 105
Thread 6 returned 106
Thread 7 returned 107
Thread 8 returned 108
Thread 9 returned 109
Main thread done.
```

- Must "thread returned" print in order?
- What is maximum # of threads that exist when thread 5 prints hello?
- Minimum?
- Why aren't any messages interrupted mid-string?

Create/Join Concurrency



- Threads can create children, and wait for their completion
- Data only shared before fork/after join
- Examples:
 - Web server: fork a new thread for every new connection
 - As long as the threads are completely independent
 - Merge sort
 - Parallel memory copy

Ex: bzero



```
void blockzero (unsigned char *p, int length) {
    int i, j;
    thread t threads[NTHREADS];
    struct bzeroparams params[NTHREADS];
// For simplicity, assumes length is divisible by NTHREADS.
for (i = 0, j = 0; i < NTHREADS; i++, j += length/NTHREADS) {
        params[i].buffer = p + i * length/NTHREADS;
        params[i].length = length/NTHREADS;
        thread create p(&(threads[i]), &go, &params[i]);
    for (i = 0; i < NTHREADS; i++) {
        thread join(threads[i]);
```

Thread Data Structures



Shared State

Thread 1's Per–Thread State

Thread 2's Per-Thread State

Code

Global

Variables

Thread Control Block (TCB)

Stack

Information

Saved

Registers

Thread

Metadata

Thread Control Block (TCB)

Stack
Information

Saved

Thread

Registers

Metadata

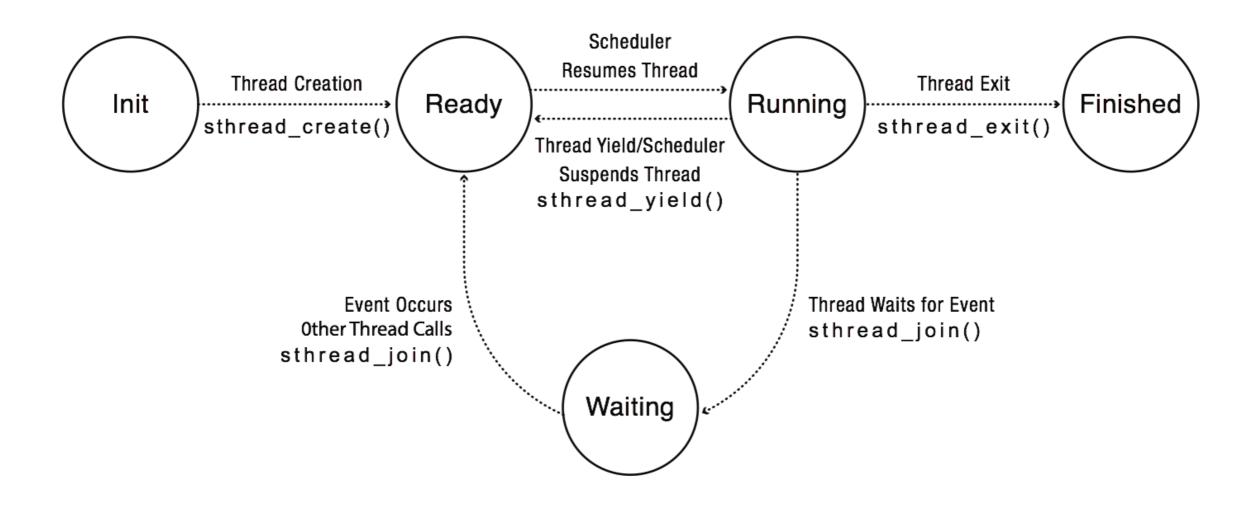
Heap

Stack

Stack

Thread Lifecycle





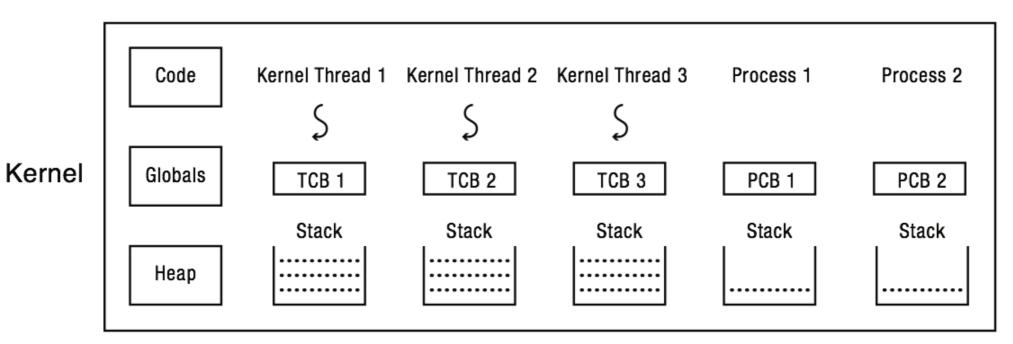
Thread Implementations



- Kernel threads
 - Thread abstraction only available to kernel
 - To the kernel, a kernel thread and a single threaded user process look quite similar
- Multithreaded processes using kernel threads
 - Kernel thread operations available via syscall
- User-level threads
 - Thread operations without system calls

Multithreaded OS Kernel





User-Level Processes

Process 1 Thread Stack	Process 2 Thread Stack
Stack	Stack
Code	Code
Globals	Globals
Неар	Неар

Implementing Threads



- Thread_fork(func, args)
 - Allocate thread control block
 - Allocate stack
 - Build stack frame for base of stack (stub)
 - Put func, args on stack
 - Put thread on ready list
 - Will run sometime later (maybe right away!)
- stub(func, args):
 - Call (*func)(args)
 - If return, call thread_exit()

Implementing Threads



- Thread_Exit
 - Remove thread from the ready list so that it will never run again
 - Free the per-thread state allocated for the thread

Ex: Two Threads call Yield



Thread 1's instructions

"return" from thread_switch
into stub
call go
call thread_yield
choose another thread
call thread_switch
save thread 1 state to TCB
load thread 2 state

Thread 2's instructions

"return" from thread_switch
into stub
call go
call thread_yield
choose another thread
call thread_switch
save thread 2 state to TCB
load thread 1 state

Processor's instructions

"return" from thread switch into stub call go call thread yield choose another thread call thread switch save thread 1 state to TCB load thread 2 state "return" from thread_switch into stub call go call thread_yield choose another thread call thread switch save thread 2 state to TCB load thread 1 state return from thread_switch return from thread_yield call thread_yield choose another thread call thread_switch

return from thread_switch return from thread_yield call thread_yield choose another thread call thread_switch

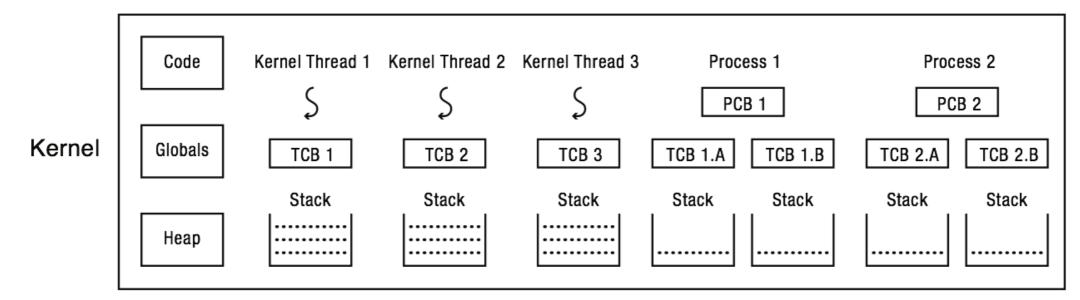


Take 1:

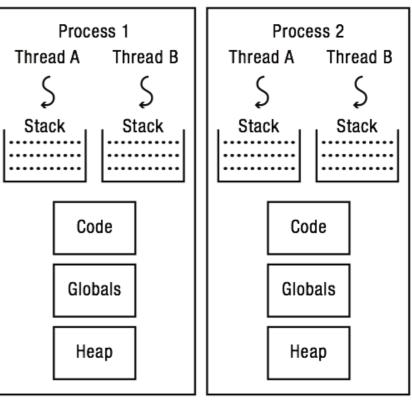
- User thread = kernel thread (Linux, MacOS)
 - System calls for thread fork, join, exit (and lock, unlock,...)
 - Kernel does context switch
 - Simple, but a lot of transitions between user and kernel mode



Take 1:



User-Level Processes





Take 2:

- Green threads (early Java)
 - User-level library, within a single-threaded process
 - Library does thread context switch
 - Preemption via upcall/UNIX signal on timer interrupt
 - Use multiple processes for parallelism
 - Shared memory region mapped into each process



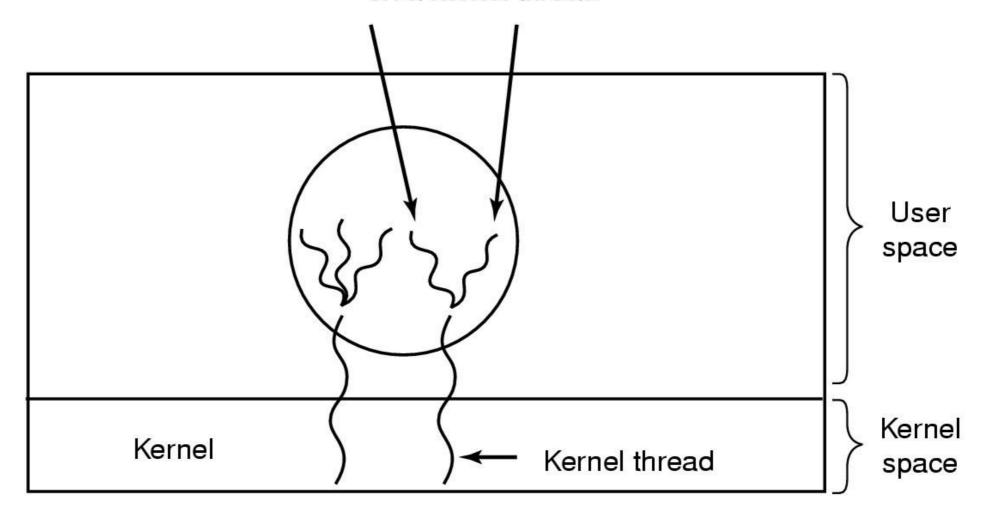
Take 3:

- Scheduler activations (Windows 8):
 - Kernel allocates processors to user-level library
 - Thread library implements context switch
 - Thread library decides what thread to run next
- Upcall whenever kernel needs a user-level scheduling decision:
 - Process assigned a new processor
 - Processor removed from process
 - System call blocks in kernel



Take 3: (What's old is new again)

Multiple user threads on a kernel thread



M:N model multiplexes N user-level threads onto M kernel-level threads

Good idea? Bad Idea?